Introduction to Analytic Thomography

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Calendar of seminars

- May 14 Introduction to Analytic Tomography general introduction, Radon tranform, FBP
- May 21 Reconstruction in X-ray computed tomography

iterative methods, kernel methods

- May 28 The mathematics behind SPECT/TC reconstruction analytical and iterative hybrid reconstruction
 - June 4 Resolution of a Gamma Camera: experimental data and analytical formula

resolution formulas

June 11 An alternative Radon transform for the correction of partial volume effect

a modest proposal ..

Axial Tomography machines provide result of some circular acquisitions. We discuss algorithms of reconstruction from projections and their efficiency in a few cases

- transmission tomography (e.g. CT): an electromagnetic ray passes trough the patient and is detected at the exit in order to get a morphological analysis of its interior.
- emission tomography (e.g. PET, SPECT): a radioactive tracer is injected into the patient and detected by the machine in order to make an internal functional analysis of the organs.
- hybrid tomography (e.g. SPECT/CT, SPECT/MRI): two simultaneous analysis.

We will focus on CT, SPECT and SPECT/CT problems.

What is Analytic Tomography Resolution and other technical issues

Transmission tomography



What is Analytic Tomography Resolution and other technical issues

Emission tomography



Rays

What is Analytic Tomography Resolution and other technical issues

Resolution

$$R_c = D\left(1 + \frac{x+c}{L_{eff}}\right)$$

The resolution of the machine depends on the collimator resolution and on the intrinsic resolution (the resolution of the crystal and the electronics).

$$R_s = \sqrt{R_c^2 + R_i^2}$$









What is Analytic Tomography Resolution and other technical issues



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In order to model correctly the tomography machine we will make some assumptions:

- all rays have no width and we can consider them as straight lines.
- all rays at angle θ are parallel.
- the machine runs *l* scans at the angles (θ₁,...,θ_l); the detectors move on a circle (typically *l* = 120,60).
- for each scan $j \in 1, ..., l$ the machine gets p linear samples (typically p = N, or p = 128 or p = 64).
- the total time of acquisition is relatively short so is indifferent to run an acquisition before or after another one.
- the reconstructed image has dimension $N \times N$ (typically N = 128 or N = 64).

If a ray passes through a body, it will be subject to attenuation. The Beer's law says that if I(x) is the intensity of a ray and A(x) the attenuation coefficient of the point x, then

$$\frac{\Delta I}{\Delta x} = -A(x)I(x)$$

that is, by integrating:

$$\int_{x_0}^{x_1} A(x) dx = -\int_{x_0}^{x_1} \frac{dI}{I} = -\ln(I(x_1) - I(x_0)).$$

In transmission tomography, in 2 dimensions, the Beer's law corresponds to the Radon transform (RT), defined as the integral over a line

$$\mathcal{R}f(t, heta) = \int_{\ell_{(t, heta)}} f = \int_{\mathbb{R}^2} f(ar{x}) \delta(t - ar{x} \cdot ar{ heta}) \ dar{x}$$

with $\bar{x} = (x, y)$, $\bar{\theta} = (\cos \theta, \sin \theta)$

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with $\bar{x} = (x, y)$, $\bar{\theta} = (\cos \theta, \sin \theta)$ or equivalently:

$$\mathcal{R}f(t,\theta) = \int_{\mathbb{R}} f(t\cos\theta - s\sin\theta, t\sin\theta + s\cos\theta) \, ds = \int_{\mathbb{R}} f(t\bar{\theta} + s\bar{\theta}^{\perp}) \, ds$$

with $\bar{\theta}^{\perp} = (-\sin\theta, \cos\theta).$

Beer's Law Radon Transform Backprojection Attenuated transform



$$\mathcal{R}f(t,\theta) = \int_{\mathbb{R}} f(t\cos\theta - s\sin\theta, t\sin\theta + s\cos\theta) \, ds$$

where

Beer's Law Radon Transform Backprojection Attenuated transform

Now we ask for every point (x, y) which is the average of the rays that pass through that point. This question is answered by the adjoint operator to \mathcal{R} , called Backprojection operator

$$\mathcal{R}^* g(x, y) = \frac{1}{|S^1|} \int_{S^1} g(x \cos \theta + y \sin \theta, \theta) \, d\theta =$$
$$\frac{1}{|S^1|} \int_{\mathbb{R} \times S^1} g(s, \theta) \delta(s - \bar{x} \cdot \bar{\theta}) \, ds d\theta$$
$$S^1 = [0, \pi] \text{ or } S^1 = [0, 2\pi]$$

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Warning

 \mathcal{R}^* is not the inverse transform of \mathcal{R} . In fact $\mathcal{R}^*\mathcal{R}f(\bar{x}) = \frac{2}{|\bar{x}|} * f$

Beer's Law Radon Transform Backprojection Attenuated transform

Why π or 2π ?

Beer's Law Radon Transform Backprojection Attenuated transform

Why π or 2π ?



In the case of emission tomography things are more complicated. From Beer's law we obtain that

$$I(x_1) = I(x_0) \exp\left(-\int_{x_0}^{x_1} A(x) dx\right)$$

Suppose to know the attenuation coefficient, say $a(\bar{x})$, we want to obtain the radioactivity $f(\bar{x})$ by its angular projections.

Beer's Law Radon Transform Backprojection Attenuated transform

We define the attenuated Radon transform (briefly AtRT)

$$\mathcal{R}_{\mathsf{a}}f(t, heta) = \int_{\ell_{(t, heta)}} e^{-\mathcal{D}\mathsf{a}(ar{x}, heta+\pi)}f(ar{x})$$

Beer's Law Radon Transform Backprojection Attenuated transform

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where $\ensuremath{\mathcal{D}}$ is the Divergent beam transform defined as follows

$$\mathcal{D}h(\bar{x},\theta) = \int_0^{+\infty} h(x+t\cos\theta, y+t\sin\theta) \ dt = \int_0^{+\infty} h(\bar{x}+t\bar{\theta}) \ dt$$

Beer's Law Radon Transform Backprojection Attenuated trans<u>form</u>

Then in the CT case we have to solve the following problem

RT problem

Given g projection data find f such that $\mathcal{R}f = g$

while in SPECT case we can approximate f with the solution of the previous problem

Beer's Law Radon Transform Backprojection Attenuated trans<u>form</u>

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AtRT problem

Given g projection data and a attenuation map find f such that $\mathcal{R}_a f = g$

Beer's Law Radon Transform Backprojection Attenuated trans<u>form</u>

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Given g projection data and a attenuation map find f such that $\mathcal{R}_a f = g$

to estimate the attenuation map we may need a simultaneous CT tomography \longrightarrow SPECT/CT.

Filtered Backprojection Error bound

Central Slice Theorem

Let f be a Fourier and Radon transformable function. Then

$$\mathcal{F}_{2}f(T\cos\theta,T\sin\theta)=\mathcal{F}(\mathcal{R}f)(T,\theta)$$

Where we mean for \mathcal{F}_2 the 2-dimensional Fourier transform and \mathcal{F} the 1-dimensional Fourier transform applied only to the variable *t*.

Filtered Backprojection Error bound



Filtered Backprojection Error bound

Theorem (Inversion of the Radon transform)

$$f = rac{1}{2} \mathcal{R}^* \left[\mathcal{F}^{-1}(|
u|\mathcal{F}(\mathcal{R}f))
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where we mean that the direct and inverse Fourier transform is applied only to the variable t.

Filtered Backprojection Error bound

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As known the previous formula is numerically inaccurate. Then we use $w(\nu) = p(\nu)|\nu|$ instead of $|\nu|$, with p a low-pass filter, getting the approximated

Filtered Back Projection formula (FBP)

$$f \cong \frac{1}{2} \mathcal{R}^* \left[\mathcal{F}^{-1}(w(\nu)\mathcal{F}(\mathcal{R}f)) \right]$$

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Filtered backprojection



Unfiltered backprojection



Original phantom f(x,y)



sinogram: Radon transom Rf(s,theta)

Introduction Mathematical modeling of problem Analytical methods Experiments

Filtered Backprojection Error bound

Filtered Backprojection Error bound

Theorem (Error estimate)

Let $f \in C_0^{\infty}(B(0,1))$ be a *b*-band-limited function, and let $g = \mathcal{R}f$ be reliably sampled. Let \tilde{f} be the FBP reconstruction, then

$$\|f - \tilde{f}\|_{L^{\infty}(\mathbb{R}^2)} \le 2|S^1| \|w_b\|_{L^1(\mathbb{R})} \|g - \tilde{g}\|_{L^{\infty}(\mathbb{R} \times S^1)} + |e_3|$$

with e_3 the quadrature error of the backprojection integral.

Filtered Backprojection Error bound

Why these assumptions?

Filtered Backprojection Error bound

Why these assumptions?



Analytical methods



A test for the error bound using the standard "Ram-Lack" filter.

Essential bibliography

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Hansen P.C., Hansen M., *AIR Tools - A MATLAB Package of Algebraic Iterative Reconstruction Methods*, Journal of Computational and Applied Mathematics, 2011

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- Toft P., *The Radon transform; theory and implementation*, Ph.D. thesis. Department of Mathematical Modeling, Technical University of Denmark, 1996